



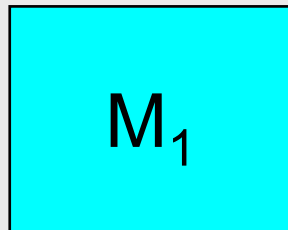
# Compositional Verification III

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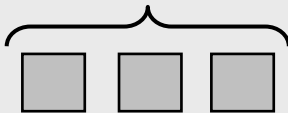
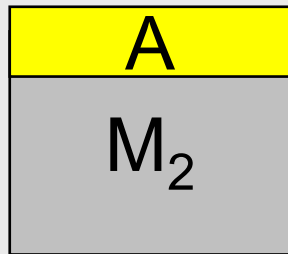
# recap in reverse order...

- ▶ assume-guarantee reasoning
- ▶ learning framework for 2 components
- ▶ weakest assumption

# assume-guarantee reasoning



satisfies P?



reasons about triples:

$\langle A \rangle M \langle P \rangle$

is *true* if whenever  $M$  is part of a system that satisfies  $A$ , then the system must also guarantee  $P$

simplest assume-guarantee rule (ASYM):

1.  $\langle A \rangle M_1 \langle P \rangle$

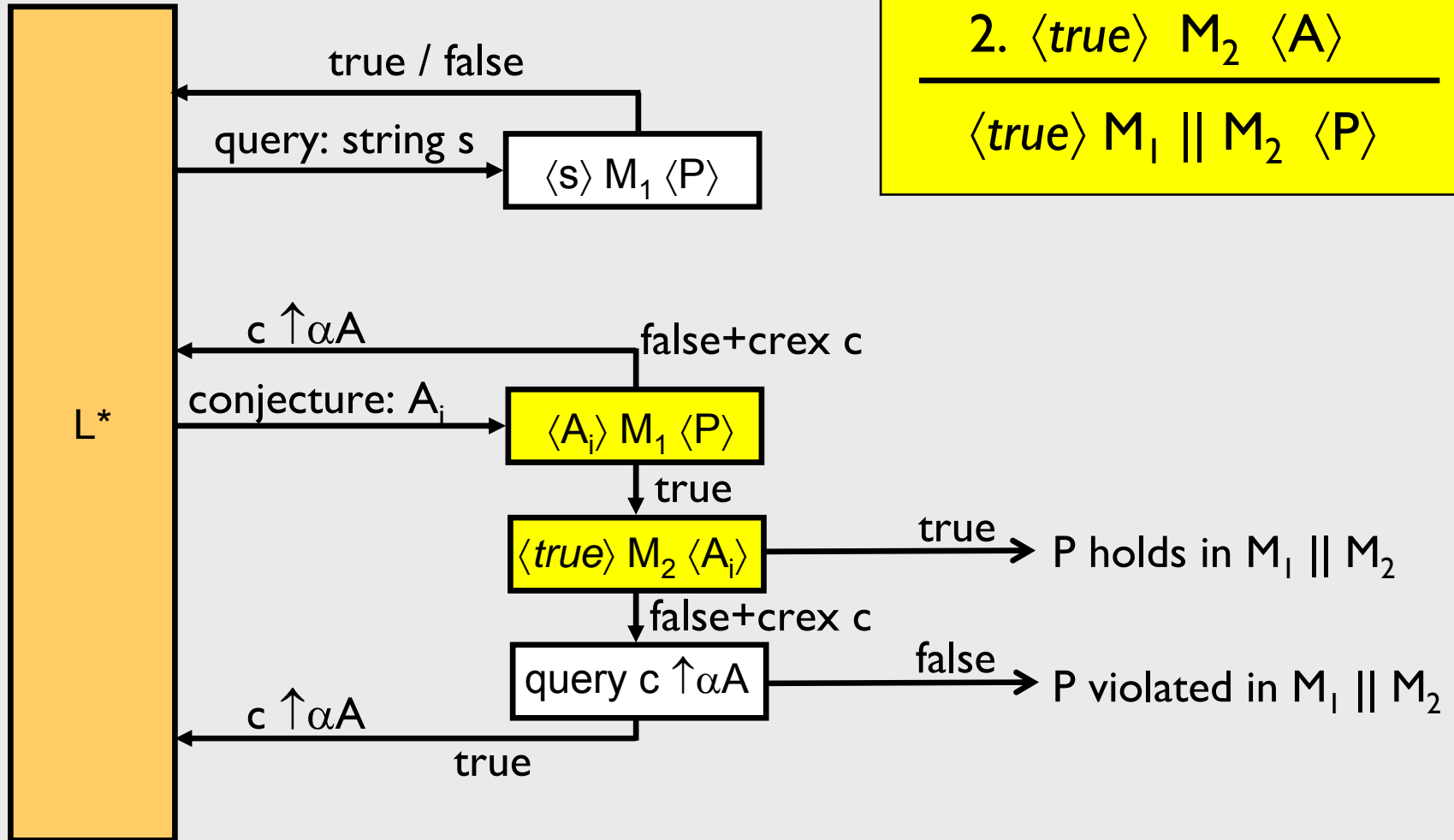
2.  $\langle true \rangle M_2 \langle A \rangle$

---

$\langle true \rangle M_1 \parallel M_2 \langle P \rangle$

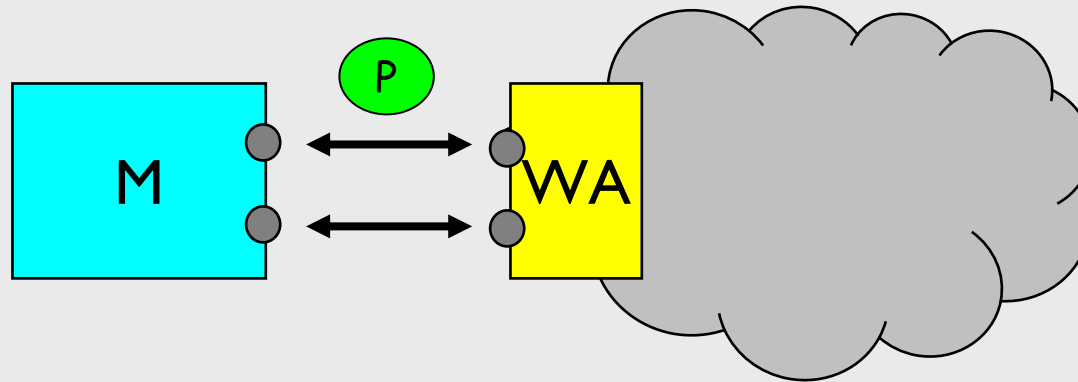
# learning assumptions for AG reasoning

1.  $\langle A \rangle M_1 \langle P \rangle$
  2.  $\langle true \rangle M_2 \langle A \rangle$
- 
- $\langle true \rangle M_1 \parallel M_2 \langle P \rangle$



assumptions conjectured by  $L^*$  are not comparable semantically

# the weakest assumption

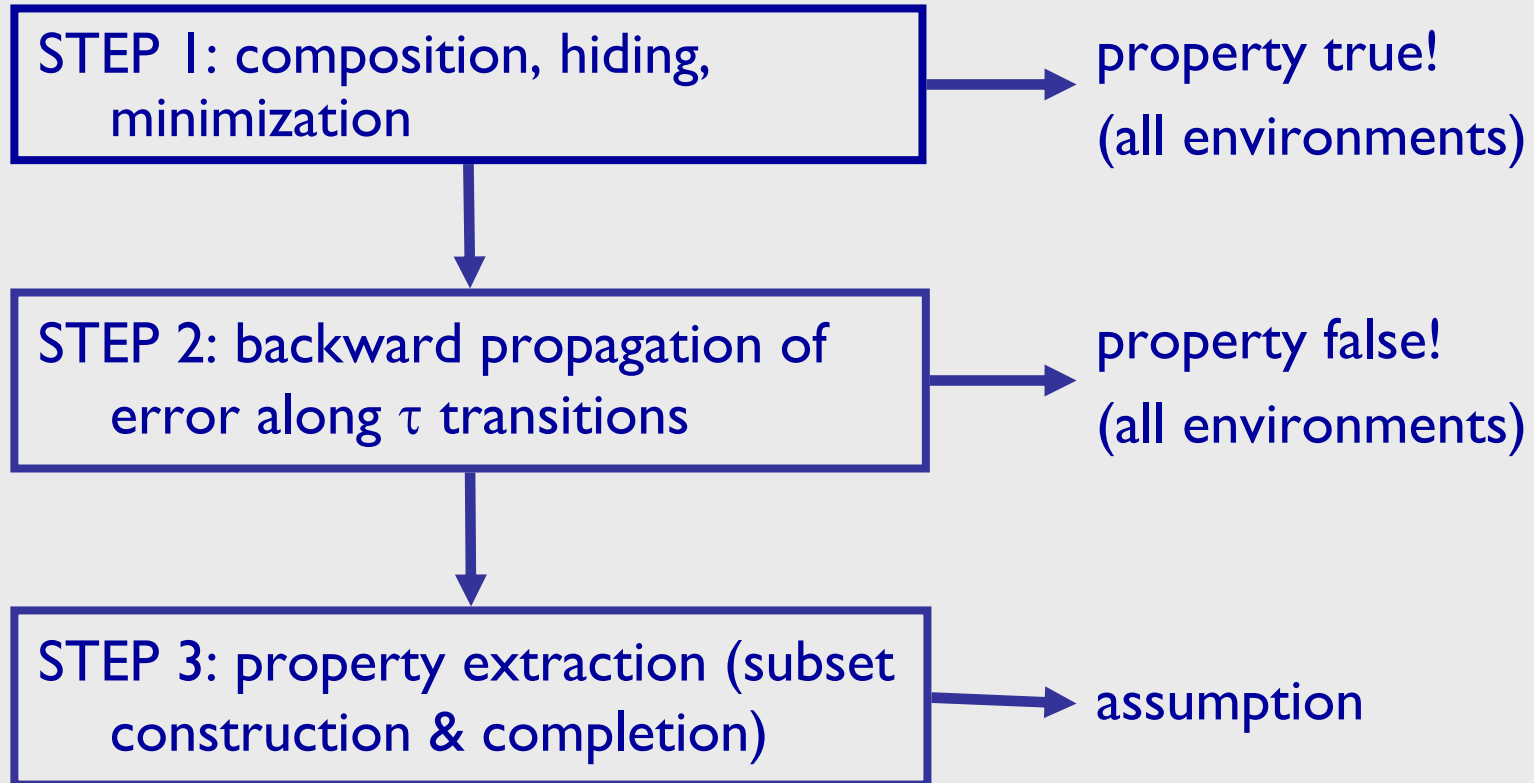


▶ given component  $M$ , property  $P$ , and the interface  $\Sigma$  of  $M$  with its environment, generate the **weakest** environment assumption **WA** such that:  $\langle WA \rangle M \langle P \rangle$  holds

▶ weakest means that for all environments  $E$ :

$$\langle true \rangle M \parallel E \langle P \rangle \text{ IFF } \langle true \rangle E \langle WA \rangle$$

# assumption generation [ASE'02]



- ▶ assume-guarantee reasoning
  - ▶ learning framework for 2 components
  - ▶ weakest assumption
- 
- ▶ interface generation
  - ▶ implementations & applications
  - ▶ other approaches

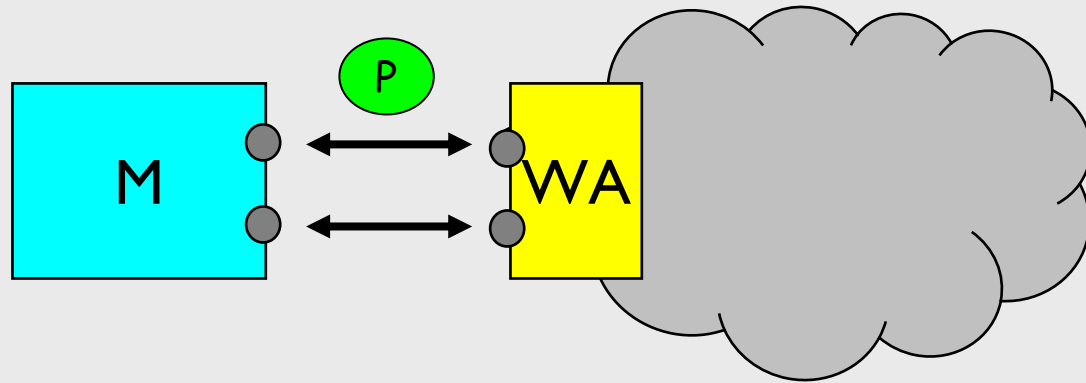
# interface generation

- ▶ beyond syntactic interfaces
  - will not invoke “close” on a file if “open” has not previously been invoked
- ▶ **safe**: accept NO illegal sequence of calls
- ▶ **permissive**: accept ALL legal sequences of calls

safe & permissive interface = weakest assumption



# learning, again...



**iterative solution + intermediate results**

L\* learner

the oracle

(queries)

should word  $w$  be included in  $L(A)$ ?

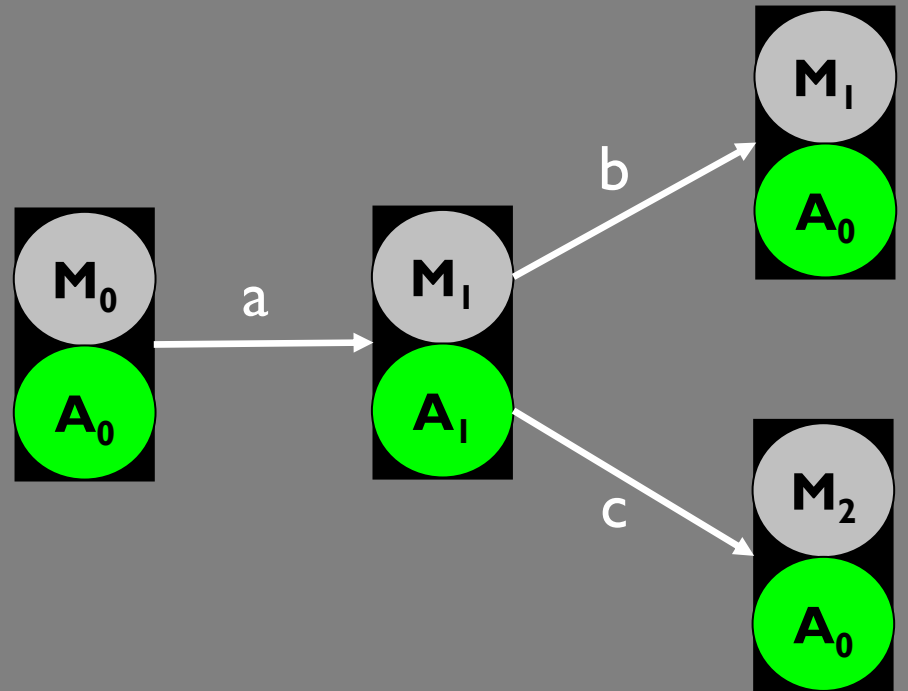
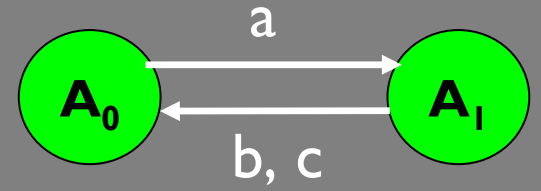
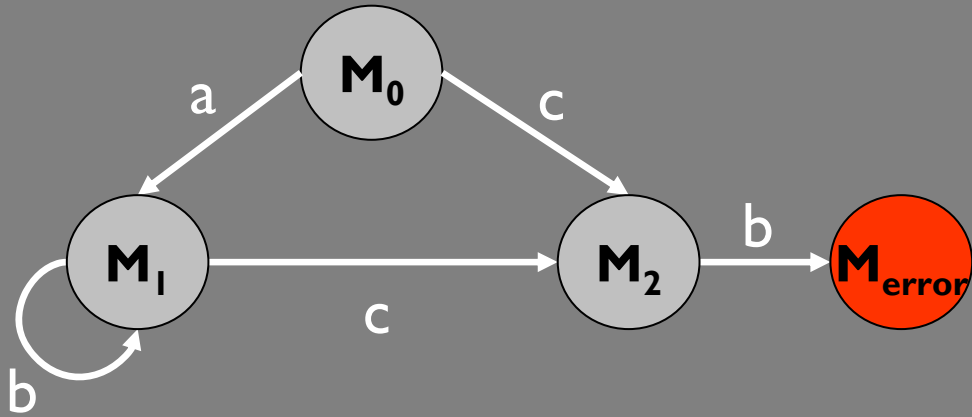
yes / no

(conjectures)

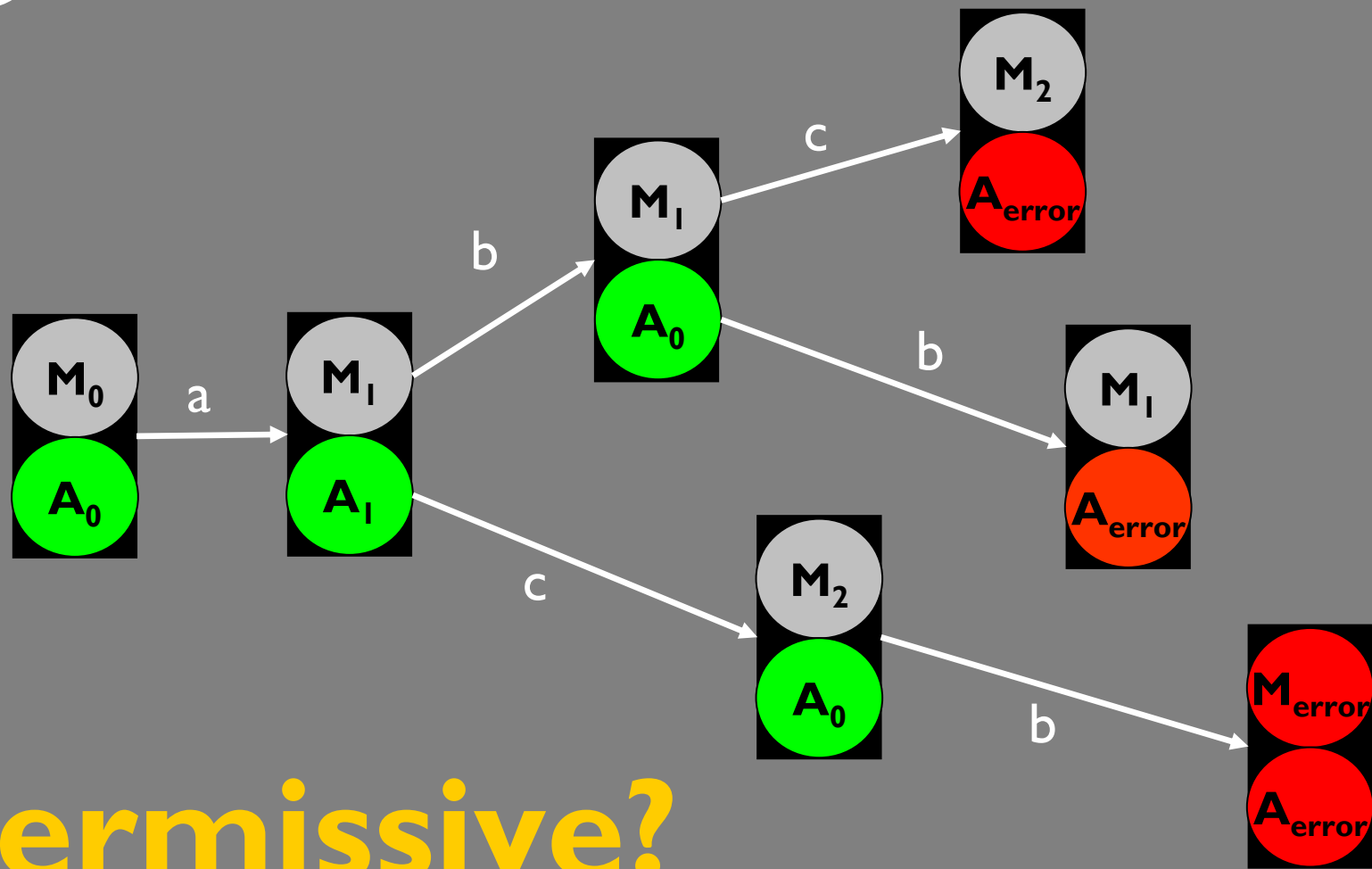
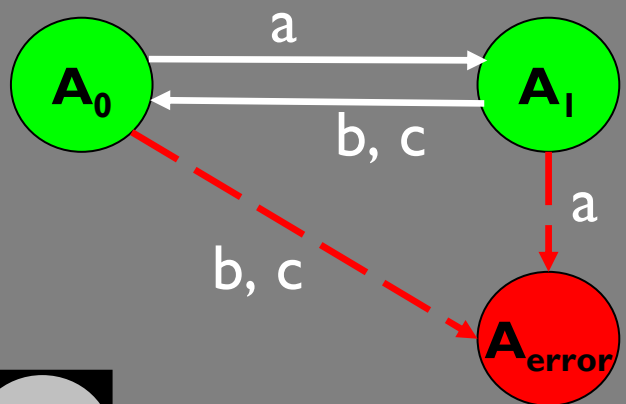
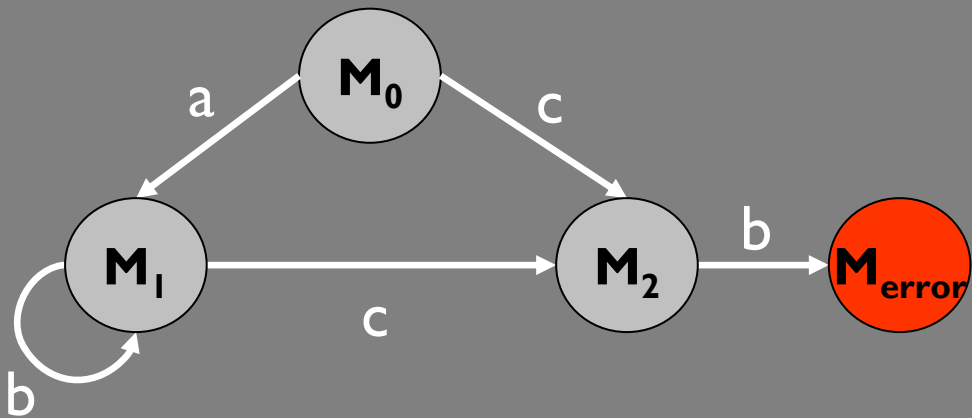
here is an  $A$  – is it safe & permissive?

yes!

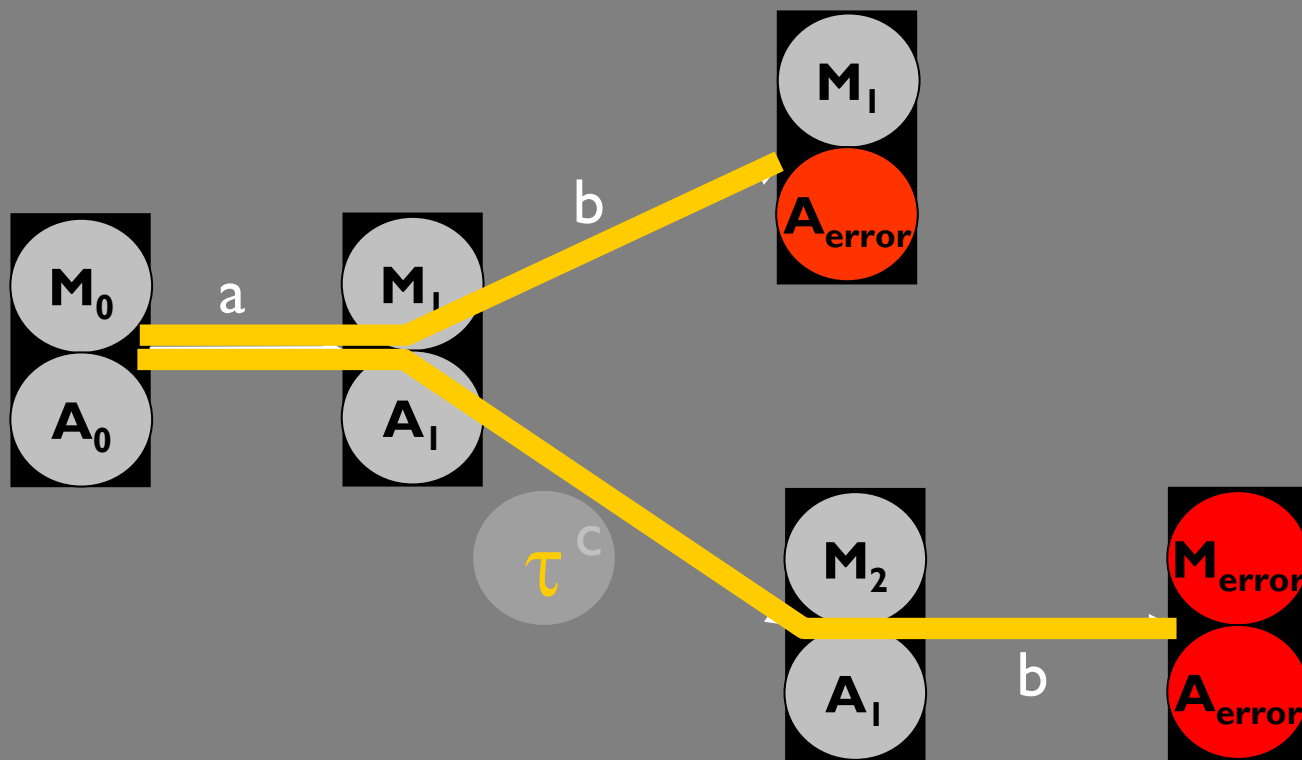
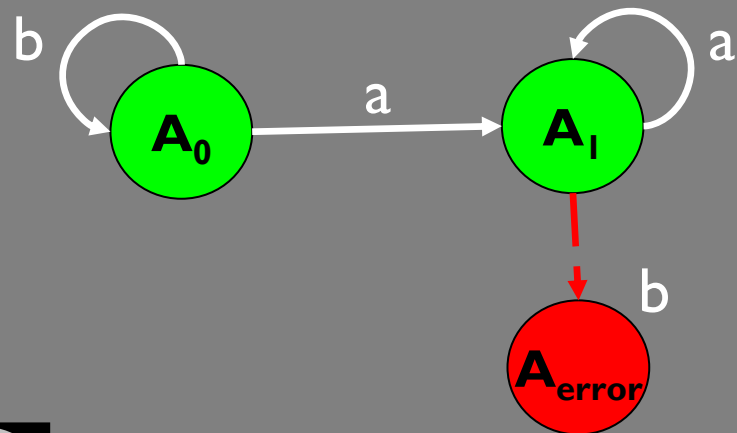
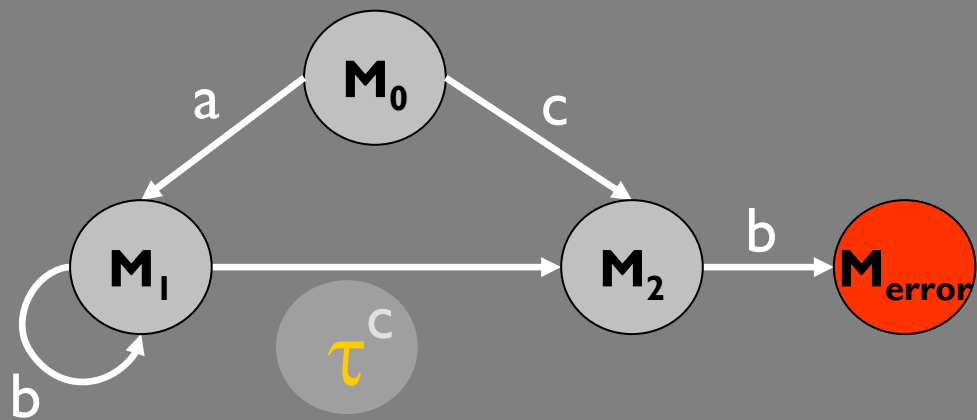
no: word  $w$  should (not) be in  $L(A)$



safe?



permissive?



problem

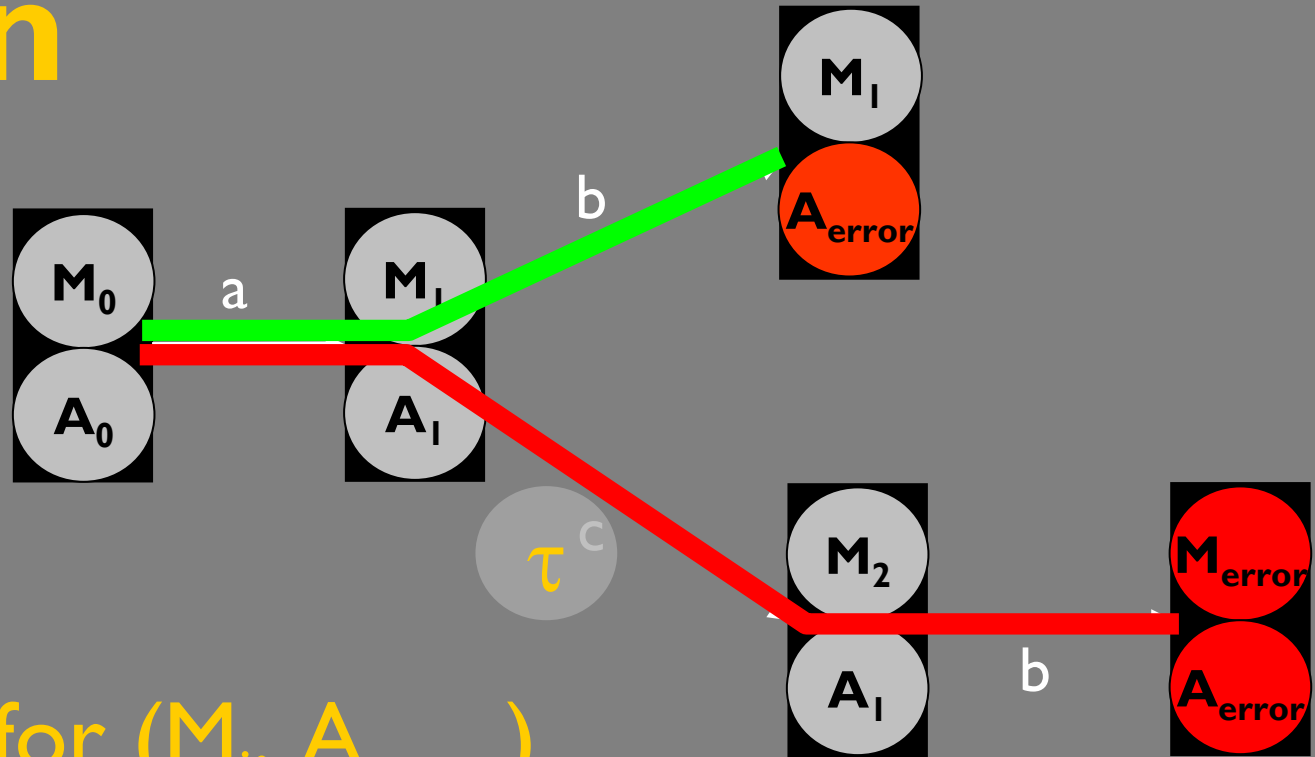
queries (simulate / model check)

conjecture – safe (model check)

conjecture – permissive?

Alur et al, 2005, Henzinger et al, 2005

# solution



model check for  $(M_i, A_{error})$

reached  $(M_i, A_{error})$  by “a b”

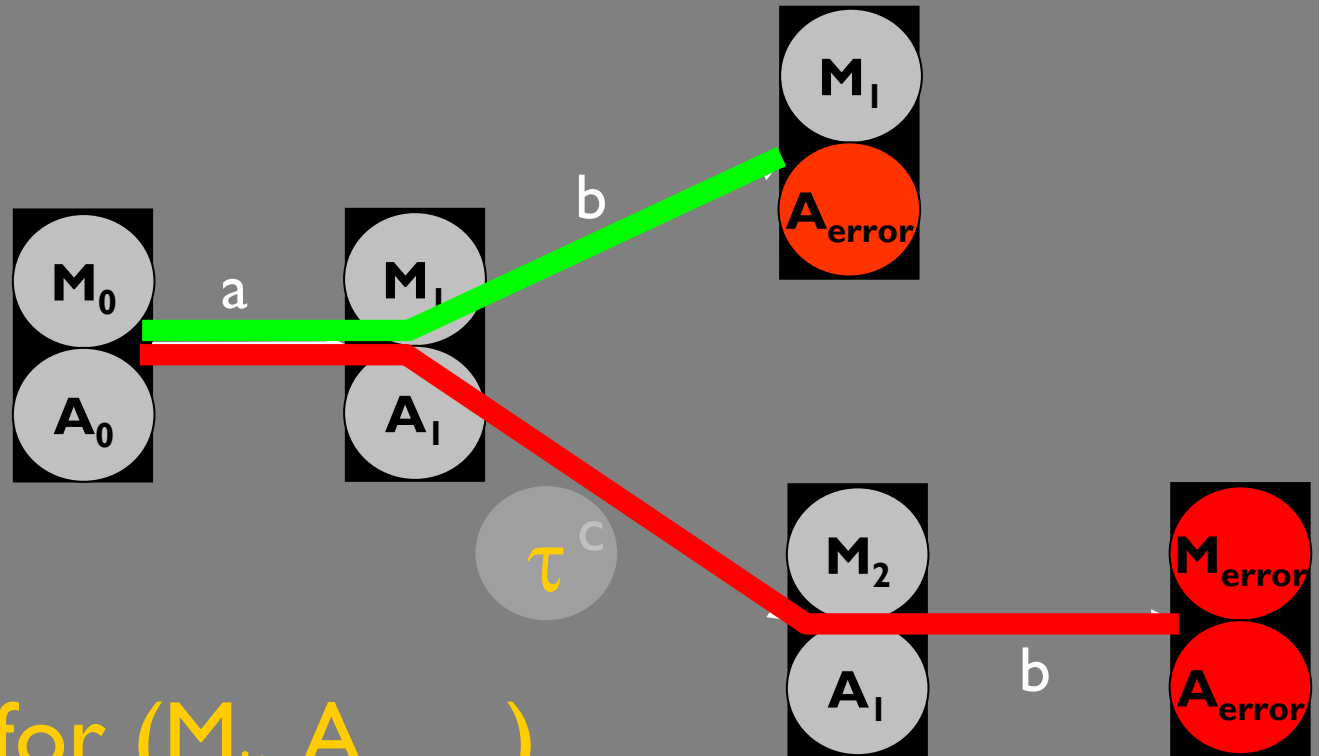
query “a b”

no (“a b” should not be in A)

backtrack and continue search...

invoke a model checker  
**within** a model checker?





model check for  $(M_i, A_{error})$

reached  $(M_1, A_{error})$  by “a b”

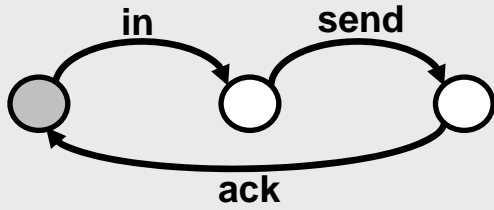
if (memoized( “a b” ) == no)

backtrack and continue search...

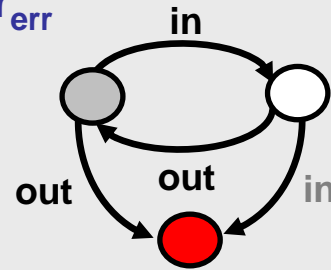
# example

## module M

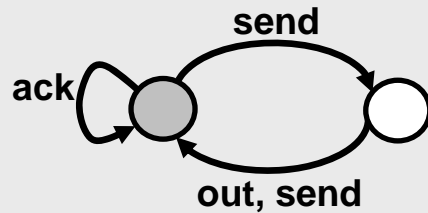
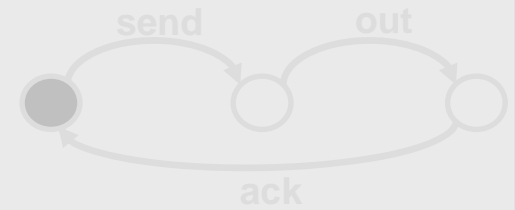
### Input



### Order<sub>err</sub>

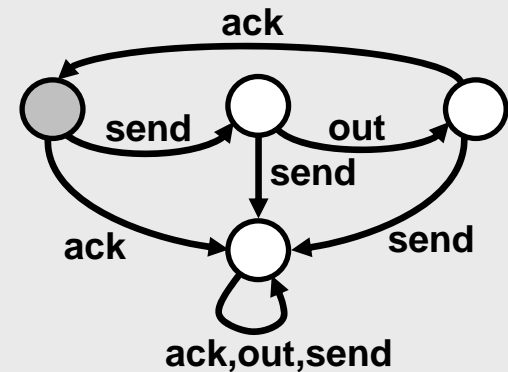


### Output



assumption learned for  
AG reasoning

$\langle \text{ack, out} \rangle ?$

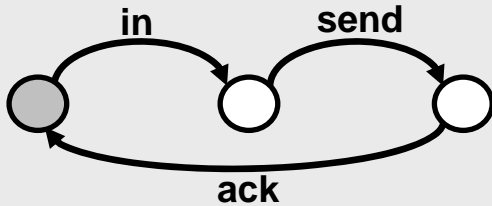


weakest assumption

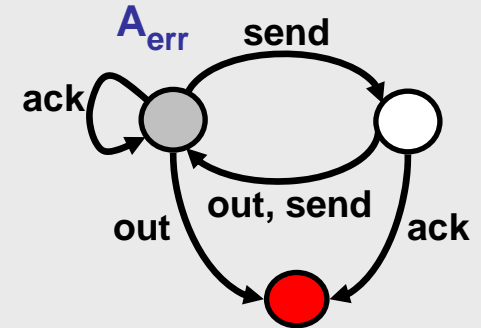
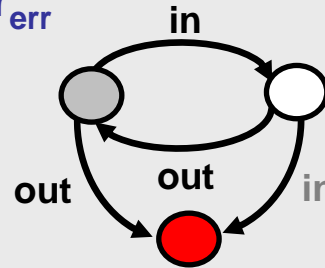
# complete module for permissiveness check

## module M

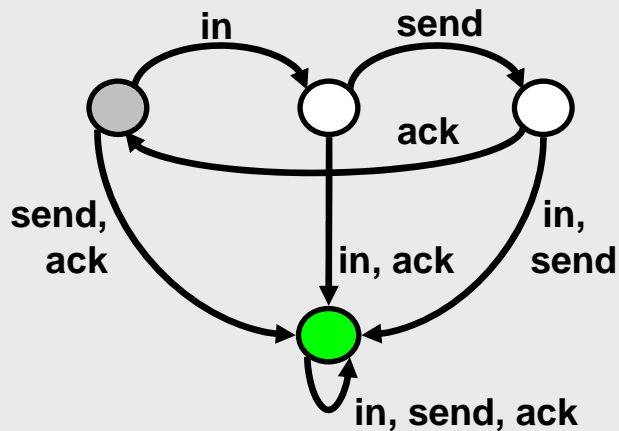
### Input



### Order\_err



### Complete\_Input



- queries performed on  $\text{Input} \parallel \text{Order}_{\text{err}}$
- safety checked on  $\text{Input} \parallel \text{Order}_{\text{err}} \parallel A_{\text{err}}$
- permissiveness performed on  $\text{Complete\_Input} \parallel \text{Order}_{\text{err}} \parallel A_{\text{err}}$

check reachability of states:  
(sink, \*, error) or (\*, non error, error)

**< ack, out >: (sink, error, error)**

in summary...

generate **precise** component interfaces

resolve non-determinism

**dynamically & selectively**

# JavaPathfinder

UML statecharts

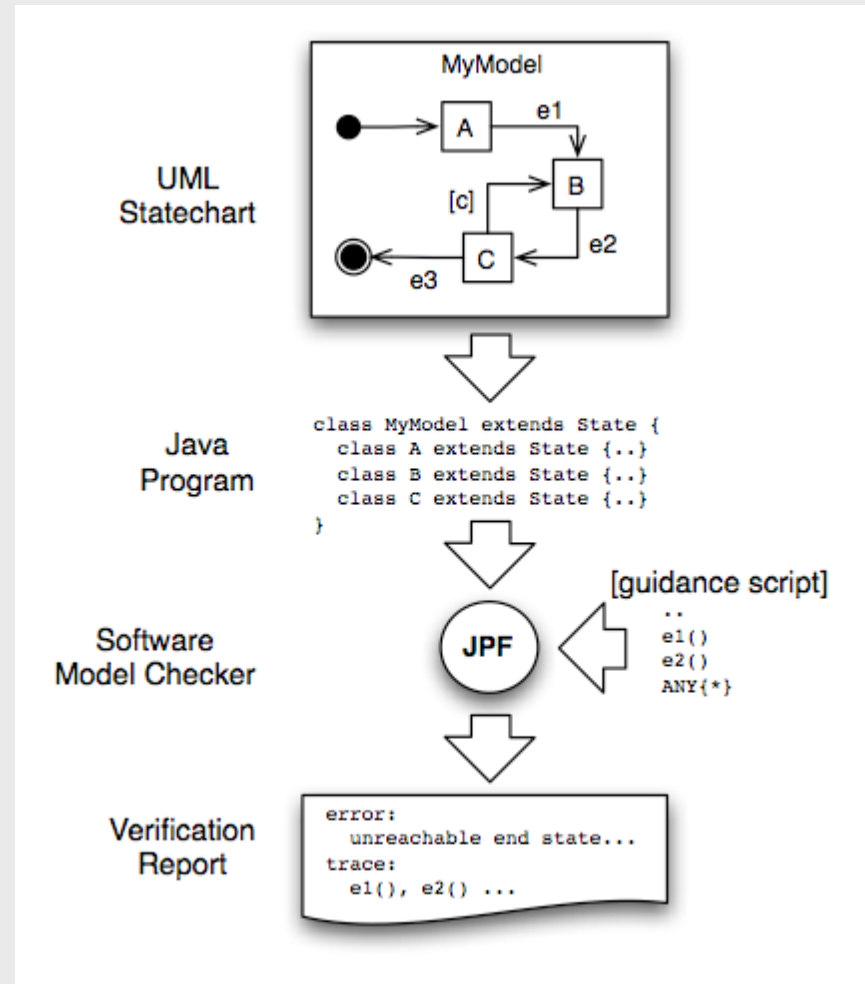
assume-guarantee reasoning

interface generation / discharge

extensions/cv  
<http://javapathfinder.sourceforge.net>

# UML framework in JPF

- ▶ JPF supports model checking of UML state-machines with an approach that consists of three steps:
  - translate the UML model into a corresponding Java program, using JPF's state chart (sc) extension and application model
  - choose model properties to verify, and configure verification tools accordingly
  - optionally provide a guidance script that represents the environment of the model (external event sequence)



# example

```
package ICSETutorial;

import gov.nasa.jpf.sc.State;

public class Input extends State {

    class S0 extends State {

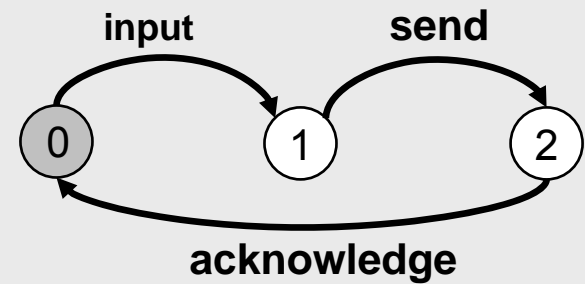
        public void input() {
            setNextState(s1);
        }
    } S0 s0 = makeInitial(new S0());

    class S1 extends State {

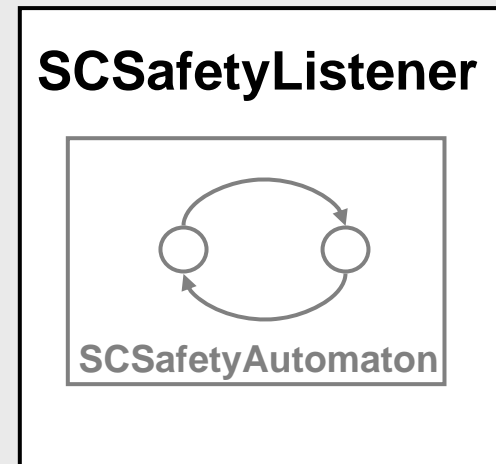
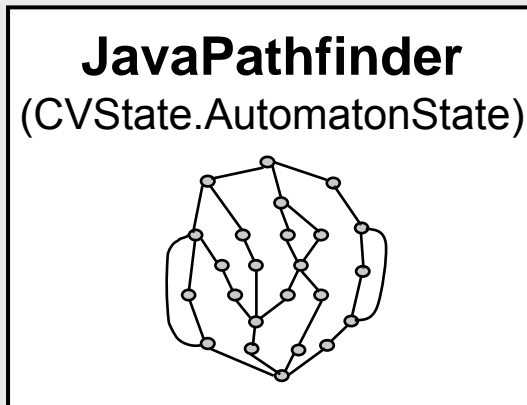
        public void send() {
            setNextState(s2);
        }
    } S1 s1 = new S1();

    class S2 extends State {

        public void acknowledge() {
            setNextState(s0);
        }
    } S2 s2 = new S2();
}
```



# AG reasoning in JPF





# assumptions

## ▶ choiceGeneratorAdvanced

- if selected action leads assumption to error state then do “vm.getState().setIgnored(true)” (**backtrack**)

## ▶ instructionExecuted

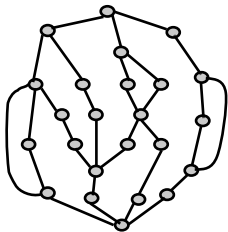
- advance automaton & set CVState.AutomatonState

## ▶ stateBacktracked

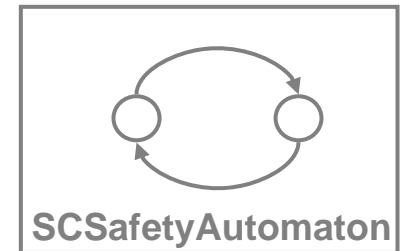
- get CVState.AutomatonState

### JavaPathfinder

(CVState.AutomatonState)



### SCSafetyListener



# properties

## ▶ instructionExecuted

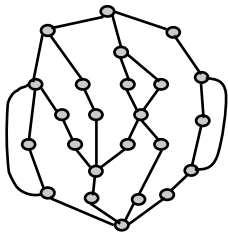
- advance automaton & set `CVState.AutomatonState`
- if automaton reaches error state, then `check()` returns false

## ▶ stateBacktracked

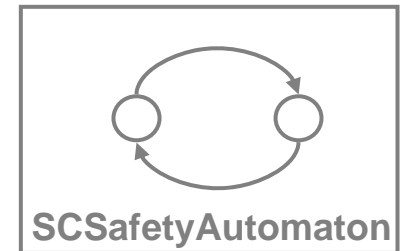
- get `CVState.AutomatonState`

### JavaPathfinder

(`CVState.AutomatonState`)



### SCSafetyListener



# how to...

run:

gov.nasa.jpfd.JPF

with the following arguments:

```
+jpf.listener=.cv.SCSafetyListener  
+safetyListenerI.property= Foo
```

# interface generation in JPF

- ▶ queries and assumption safety checks
  - same as assume-guarantee reasoning
- ▶ assumption permissiveness check
  - requires special listener

# conformance listener

## ▶ executeInstruction

- if instruction to be executed is assertion violation, then perform “ti.skipInstruction()” (do not process exception) and “vm.getState().setIgnored(true)” (backtrack)

## ▶ instructionExecuted

- advance automaton & set CVState.AutomatonState
- if automaton reaches error state, check memoized table (why?)
  - if counterexample stored and spurious, backtrack
  - else check() returns false

## ▶ stateBacktracked

- get CVState.AutomatonState

# permissiveness check

```
boolean done = false;
while (!done){
    counterexample = null;
    ...

    SCConformanceListener assumption = new SCConformanceListener(
        new SCSafetyAutomaton(false, assume, alphabet_, "Assumption",
            CompleteModule , memoized_));
    JPF jpf = createJPFInstance(assumption, property, CompleteModule);
    jpf.run();

    Path jpfPath = assumption.getCounterexample();
    if (jpfPath != null){
        //nonerror in M & error in Aerr - this is what we are looking for

        counterexample = assumption.convert(jpfPath);
        if( query(counterexample)){ // cex is in L(A)
            done = true; // a real counterexample for L*
        } // otherwise you need to continue with your loop
    }else
        done = true; // interface is permissive
}
}
```

# how to...

run:

```
gov.nasa.jpf.tools.cv.ScRunCV
```

with the following arguments:

```
+assumption.alphabet=a,b,c
```

```
+assumption.outputFile=Foo
```

# input output example

Input component with Order Property:

```
package ICSETutorial;

import gov.nasa.jpf.sc.State;
import gov.nasa.jpf.cv.CVState;

public class InputWithProperty
extends CVState {

    class S0 extends State {

        public void input() {
            setNextState(s1);
        }

        public void output() {
            assert(false);
        }

    } S0 s0 = makeInitial(new S0());

    . . .
}
```

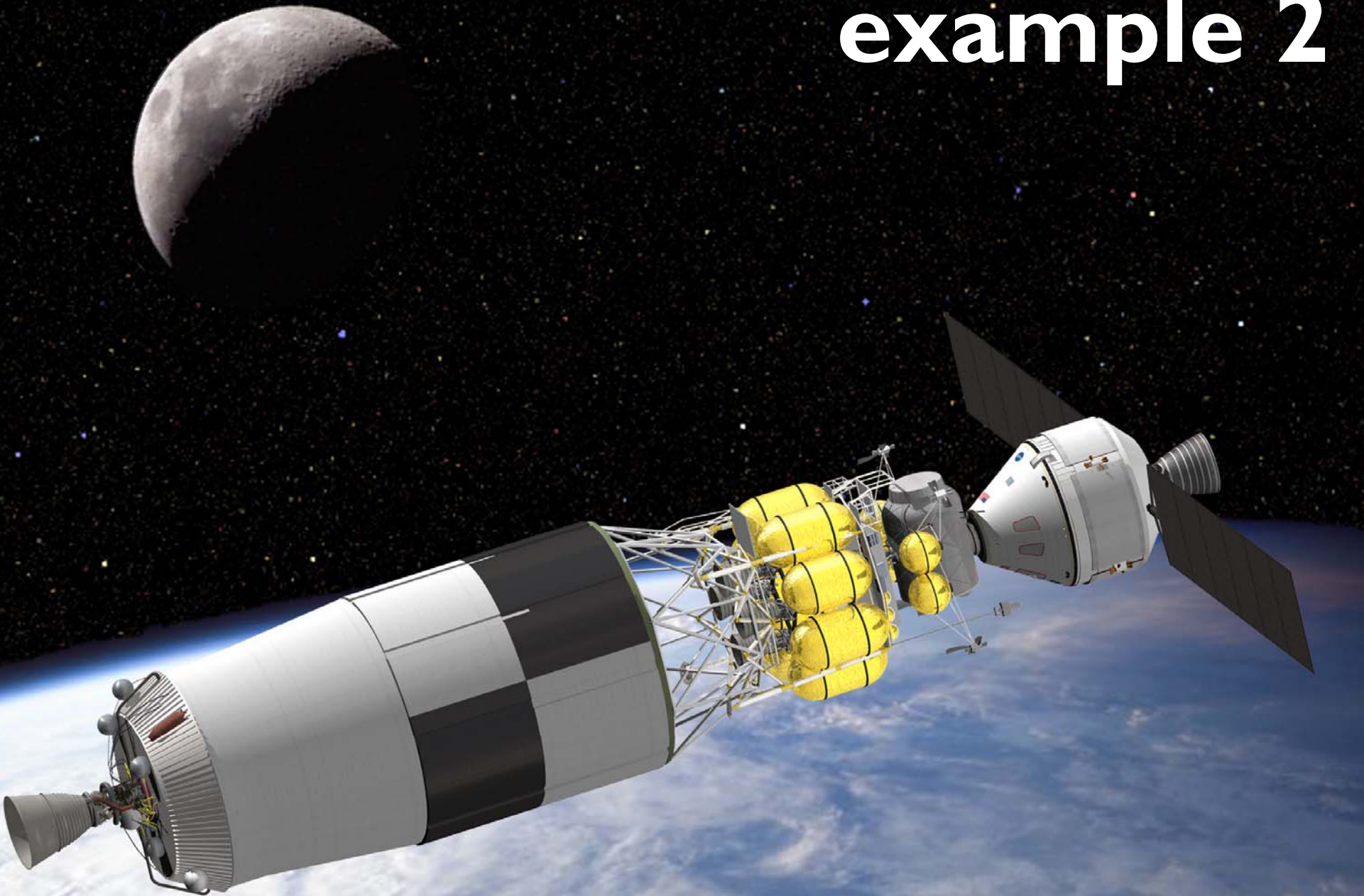
JPF Run Configuration:

- ▶ main:  
gov.nasa.jpf.tools.cv.ScRunCV
- ▶ arguments:  
+jpf.listener=.tools.ChoiceTracker  
+assumption.outputFile=  
examples/ICSETutorial/generatedAssumption  
+assumption.alphabet=output,send,acknowledge  
+jpf.report.console.property\_violation=error  
+vm.store\_steps=true  
+log.info=gov.nasa.jpf.sc  
  
ICSETutorial.InputWithProperty

```
S0 = ( send -> S2
      | acknowledge -> S1 ),
S1 = ( output -> S1
      | send -> S1
      | acknowledge -> S1 ),
S2 = ( output -> S3
      | send -> S1 ),
S3 = ( send -> S1
      | acknowledge -> S0 ).
```

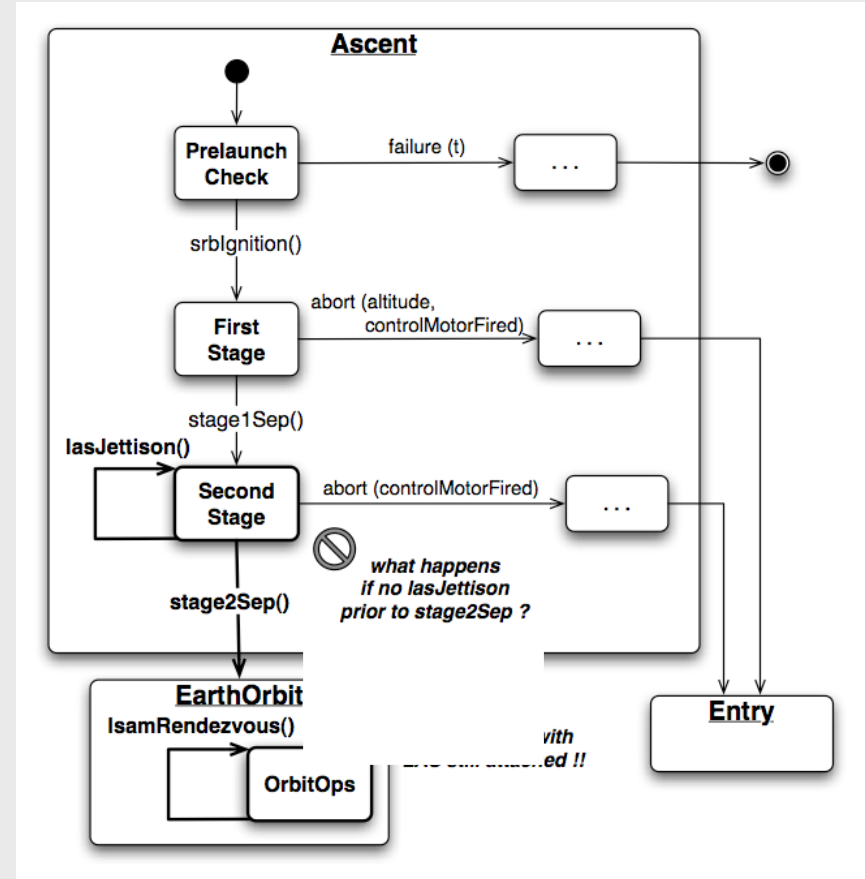


# example 2

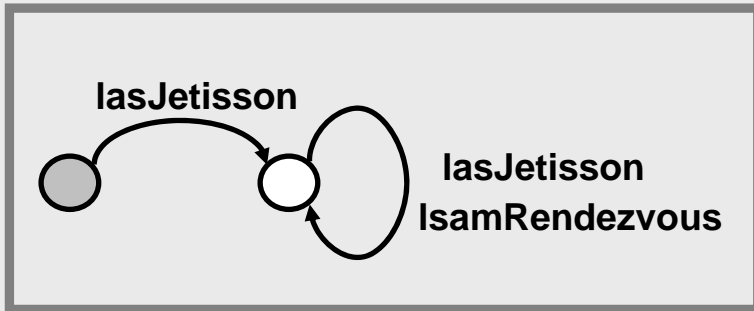


# crew exploration vehicle

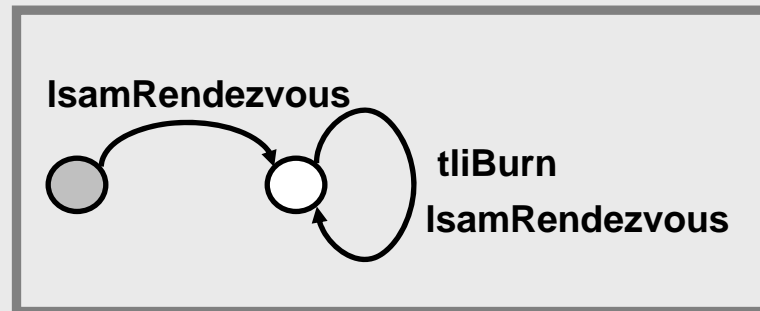
- ▶ model of the *Ascent* and *EarthOrbit* flight phases of a spacecraft
- ▶ **properties:**
  - “An event *IsamRendezvous*, which represents a docking maneuver with another spacecraft, fails if the LAS (launch abort system) is still attached to the spacecraft”
  - “Event *tliBurn* (trans-lunar interface burn) takes spacecraft out of the earth orbit and gets it into transition to the moon) can only be invoked if EDS (Earth Departure Stage) rocket is available”



## Assumption 1:



## Assumption 2:



Generated interface assumptions encode Flight Rules in terms of events

# JPF run configurations

▶ main:

gov.nasa.jpf.tools.cv.ScRunCV

▶ arguments for property 1:

**+jpf.listener=.tools.ChoiceTracker:.cv.AssertionFilteringListener**

**+assertionFilter.include=tliBurn**

+assumption.alphabet=tliBurn,lsamRendezvous

+assumption.outputFile=examples/jpfESAS/script/generatedAssumption1

+jpf.report.console.property\_violation=error

+vm.store\_steps=true

jpfESAS.CEV\_15EOR\_LOR

▶ arguments for property 2:

**+jpf.listener=.tools.ChoiceTracker:.cv.AssertionFilteringListener**

**+assertionFilter.include=lsamRendezvous**

+assumption.alphabet=lasJettison,lsamRendezvous

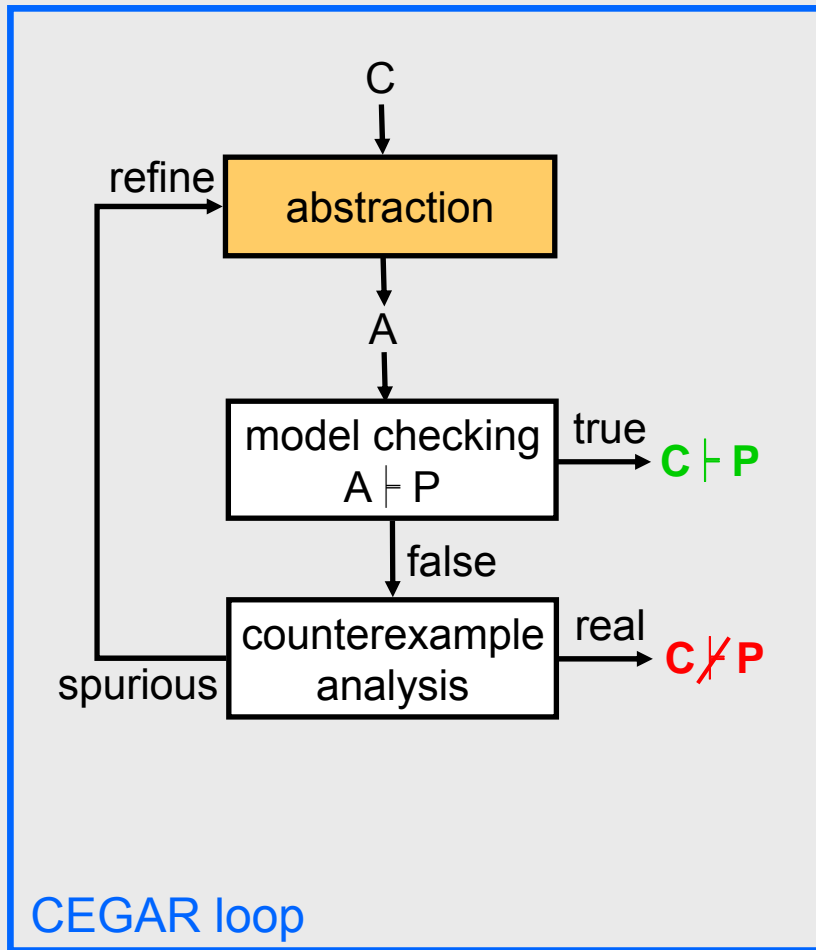
+assumption.outputFile=examples/jpfESAS/script/generatedAssumption2

+jpf.report.console.property\_violation=error

+vm.store\_steps=true

jpfESAS.CEV\_15EOR\_LOR

# CEGAR for compositional verification



- ▶ CEGAR: counterexample guided abstraction refinement – Clarke et al. 00
  - incremental construction of abstractions
  - abstractions are conservative
  - abstract counterexamples obtained may be spurious (due to over-approximation)
  - spurious counterexamples are used for abstraction refinement
- ▶ two level compositional abstraction refinement – Chaki et al. 03
  - analyze  $C_1 \parallel C_2 \parallel \dots \parallel C_n \vdash P$
  - build finite-state abstractions:  $A_1, A_2, \dots, A_n$
  - minimize:  $M_1, M_2, \dots, M_n$
  - analyze:  $M_1 \parallel M_2 \parallel \dots \parallel M_n \vdash P$ ?
  - refine based on counterexamples
- ▶ permissive interfaces – Henzinger et al. 05
  - uses CEGAR to compute interfaces
- ▶ new result at CAV'08

# assume-guarantee abstraction refinement (AGAR)

$$\begin{array}{l} 1. \langle A \rangle \quad M_1 \quad \langle P \rangle \\ 2. \langle true \rangle \quad M_2 \quad \langle A \rangle \\ \hline \langle true \rangle M_1 \parallel M_2 \langle P \rangle \end{array}$$

- ▶ build  $A$  as an abstraction of  $M_2$
- ▶  $\langle true \rangle M_2 \langle A \rangle$  holds by construction
- ▶ check Premise I:  $\langle A \rangle M_1 \langle P \rangle$
- ▶ obtained counterexamples are analyzed and used to refine  $A$
- ▶ variant of CEGAR (Counter-example Guided Abstraction Refinement) with differences:
  - use counterexample from one component ( $M_1$ ) to refine abstraction of the other component ( $M_2$ )
  - $A$  keeps information only about the interface (and abstracts away the internal information)
- ▶ implemented in LTSA; combined with alphabet refinement; compares favorably with learning approach

# other related work

- ▶ minimal separating automaton for disjoint languages  $L_1$  and  $L_2$ 
    - accept all words in  $L_1$
    - accept no words in  $L_2$
    - have the **least number of states**
  - ▶ assume-guarantee reasoning
    - minimal separating automaton for  $L(M_2)$  and  $L(M_1) \cap L(\text{coP})$
  - ▶ algorithms
    - Gupta et al. 07: query complexity exponential in the size of the minimal DFAs for the two input languages
    - Chen et al. 09: query complexity quadratic in the product of the sizes of the minimal DFAs for the two input languages. Use 3 valued DFAs
- 
- ▶ compositional verification in symbolic setting (Alur et al. 05)
  - ▶ learning omega-regular languages for liveness (Farzan et al. 08)
  - ▶ learning non-deterministic automata (Bollig et al. 09)

thank you!